

Given Name:\_\_\_\_\_ Family Name:\_\_\_\_\_

Student Number:\_\_\_\_\_ Signature:\_\_\_\_\_

**John von Neumann University  
MNB Institute**

**Empirical Panel Data (19<sup>th</sup> June, 2023)**

Instructor: Chaoyi Chen

**Final  
VERSION CODE: A  
Spring, 2023**

**Duration: 120 minutes**

**Aids Allowed: One two-sided handwritten 4 by 6 inch index card formula sheet. Only simple calculators without programming and scientific functions allowed as determined by the exam proctors. No other electronic devices permitted.**

Answer all questions.

- Multiple choice questions should be chosen by marking ✓. All other questions must include all work on the exam. No credit without work.
- Sign your exam, initial each page.
- With the sole exception of simple, non-programable, non-scientific calculators, use of electronic devices is not permitted. Determination of which calculators are permitted is at the sole discretion of the exam proctors. Please turn off your cell-phone and all other electronic devices, placing these together with any personal items at the front of the room.
- You cannot leave the room during the exam without explicit permission from the proctor.
- The total marks are provided at the end of your exam.
- Hand in your entire exam together at the end of the exam.

Do not hesitate to raise your hand if you have a question.

**Good Luck!**

## Multiple Choice

Please record all answers by marking ✓.

1. [3] Who is your instructor of this course?
  - (a) Chaoyi Chen
  - (b) Jerry Hausman
  - (c) Joe Biden
  - (d) Jackie Chan
  
2. [3] Which of following models is **not** a linear regression model?
  - (a)  $Y_i = \beta_0 + \beta_1\left(\frac{1}{X_i}\right) + \mu_i$
  - (b)  $Y_i = \beta_0 + \beta_1 \ln(X_i) + \mu_i$
  - (c)  $\ln(Y_i) = \beta_0 + \beta_1 \ln(X_i) + \mu_i$
  - (d)  $\ln(Y_i) = \ln(\beta_0) + \beta_1 X_i + \mu_i$
  
3. [3] Which of following is true for panel data?
  - (a) Order of data does not matter
  - (b) No time dimension
  - (c) Repeat observations for a specific agent over time
  - (d) Combine cross-sectional and time series issues
  
4. [3] Consider the following panel data model:

$$y_{it} = \alpha_i + \beta' x_{it} + \varepsilon_{it},$$

where  $\alpha_i$  is a scalar with  $E(\alpha_i) = 0$  for all  $i = 1, \dots, n$ ,  $\beta = (\beta_1, \beta_2, \dots, \beta_k)^\top$  is a  $k \times 1$  vector of parameter,  $x_{it} = (x_{it,1}, \dots, x_{it,k})^\top$  is a  $k \times 1$  vector of exogenous variables, and  $\varepsilon_{it}$  is an error term and assumed to be *i.i.d.* with, for all  $i = 1, \dots, n$ , and all  $t = 1, \dots, T$ ,  $E(\varepsilon_{it}) = 0$ ,  $E(\varepsilon_{it}^2) = \sigma^2$ . Now, assuming  $E(\alpha_i | x_{i1}, \dots, x_{iT}) \neq 0$ , the OLS estimator of  $\beta$  is

- (a) unbiased and consistent
  - (b) unbiased but in consistent
  - (c) biased but consistent
  - (d) biased and inconsistent
5. [3] Continue with the same information as in Question 4. The fixed effect (or LSDV) estimators of  $\beta$  and  $\alpha_i$  are
    - (a)  $\beta$ : unbiased and consistent when either  $n$ , or  $T$ , or both tend to infinity  
 $\alpha_i$ : unbiased and consistent when either  $n$ , or  $T$ , or both tend to infinity

- (b)  $\beta$ : unbiased and consistent when either  $n$ , or  $T$ , or both tend to infinity  
 $\alpha_i$ : biased and inconsistent
- (c)  $\beta$ : unbiased and consistent only when  $n$  and  $T$  both tend to infinity  
 $\alpha_i$ : unbiased and consistent when either  $n$ , or  $T$ , or both tend to infinity
- (d)  $\beta$ : unbiased and consistent when either  $n$ , or  $T$ , or both tend to infinity  
 $\alpha_i$ : unbiased and consistent only when  $T$  or both tend to infinity
6. [3] Continue with the same information as in Question 4 but now assume  $E(\alpha_i|x_{i1}, \dots, x_{iT}) = 0$ . Which of the following statement is **not** true?
- (a) The OLS estimator is biased and inconsistent
- (b) The LSDV estimator is unbiased and consistent
- (c) The GLS estimator is unbiased and consistent
- (d) The GLS estimator is the best linear unbiased estimator (BLUE)
7. [3] Continue with the same information as in Question 4 but assume we are interested in detecting whether the panel data model is a random effect model or a fixed effect model. Under the null of  $E(\alpha_i|x_{i1}, \dots, x_{iT}) = 0$ , which of the following is the **correct** test statistic we use to conduct a Hausman specification test?

(a)  $H = \left( \widehat{\beta}^{GLS} - \widehat{\beta}^{LSDV} \right)^\top \left( \text{Var}(\widehat{\beta}^{LSDV}) - \text{Var}(\widehat{\beta}^{GLS}) \right)^{-1} \left( \widehat{\beta}^{GLS} - \widehat{\beta}^{LSDV} \right)$

(b)  $H = \left( \widehat{\beta}^{GLS} - \widehat{\beta}^{LSDV} \right)^\top \left( \text{Var}(\widehat{\beta}^{GLS}) - \text{Var}(\widehat{\beta}^{LSDV}) \right)^{-1} \left( \widehat{\beta}^{GLS} - \widehat{\beta}^{LSDV} \right)$

(c)  $H = \left( \widehat{\beta}^{OLS} - \widehat{\beta}^{LSDV} \right)^\top \left( \text{Var}(\widehat{\beta}^{LSDV}) - \text{Var}(\widehat{\beta}^{OLS}) \right)^{-1} \left( \widehat{\beta}^{OLS} - \widehat{\beta}^{LSDV} \right)$

(d)  $H = \left( \widehat{\beta}^{OLS} - \widehat{\beta}^{LSDV} \right)^\top \left( \text{Var}(\widehat{\beta}^{OLS}) - \text{Var}(\widehat{\beta}^{LSDV}) \right)^{-1} \left( \widehat{\beta}^{OLS} - \widehat{\beta}^{LSDV} \right)$

8. [3] For the dynamic panel fixed effect model,

$$y_{it} = \gamma y_{i,t-1} + \alpha_i + \varepsilon_{it},$$

where we assume  $|\gamma| < 1$  and the initial condition  $y_{i0} = 0$  for all  $i$ . The dynamic bias of the LSDV estimator is from

- (a) Perfect multicollinearity
- (b) Serially correlated error
- (c) Spurious regression
- (d) Endogenous problem
9. [3] Continue with the same information as in Question 8, we now use the Anderson and Hsiao instrumental variable (IV) approach to estimate the model. The two conditions for a valid IV,  $Z_{it}$ , are

- (a)  $\text{corr}(Z_{it}, \Delta y_{it-1}) = 0$  and  $\text{corr}(Z_{it}, \Delta \varepsilon_{it}) \neq 0$   
 (b)  $\text{corr}(Z_{it}, \Delta y_{it-1}) = 0$  and  $\text{corr}(Z_{it}, \Delta \varepsilon_{it}) = 0$   
 (c)  $\text{corr}(Z_{it}, \Delta y_{it-1}) \neq 0$  and  $\text{corr}(Z_{it}, \Delta \varepsilon_{it}) = 0$   
 (d)  $\text{corr}(Z_{it}, \Delta y_{it-1}) \neq 0$  and  $\text{corr}(Z_{it}, \Delta \varepsilon_{it}) \neq 0$
10. [3] Continue with the same information as in Question 8 and now assume  $\gamma \rightarrow 1$ . What kind of problem you may have if you propose to use the Arellano and Bond (AB) estimator?
- (a) The AB estimator is inconsistent because the presence of the spurious regression  
 (b) The AB estimator is inconsistent because  $\Delta \varepsilon_{it}$  is unorthogonal to  $y_{it-j}$  for  $j \geq 1$   
 (c) The AB estimator is still consistent but the relevance condition becomes weak  
 (d) The AB estimator is still consistent but the exogeneity condition becomes weak

### Long Answer

**Please include all your work on the exam.** No credit will be given for answers without work, even when the final answer is correct.

#### 1. Long Answer I.

Consider the model with a single regressor  $x_{it}$ :

$$y_{it} = \beta_1 x_{it} + \alpha_i + u_{it}$$

where  $\alpha_i$  represents an unobserved effect fixed over time and  $u_{it}$  is a homoskedastic error term which is independent over time (t) and individuals (i). There are N randomly sampled individuals, each observed for T = 4 time periods. Assume that  $E(u_{it}|X) = 0$  for all i and  $E(u_{it}u_{is}|X) = 0$  for any t and s such that  $t \neq s$ , where X represent the stacked  $NT \times 1$  data matrix.

- (a) [10] List the OLS objective function and derive the OLS estimator of  $\beta_0$ . Show OLS estimator is unbiased when  $E(\alpha_i|x_{it}) = 0$  but biased when  $E(\alpha_i|x_{it}) \neq 0$ .

- (b) [10] Derive the within-group estimator of  $\beta_0$ . Show the within-group estimator is unbiased when  $E(\alpha_i|x_{it}) = 0$  and when  $E(\alpha_i|x_{it}) \neq 0$

- (c) [5] Derive the random effects estimator of  $\beta_0$ . Show the random effects estimator is unbiased when  $E(\alpha_i|x_{it}) = 0$  but biased when  $E(\alpha_i|x_{it}) \neq 0$ .

(d) [5] Explain how you could test the assumption that  $E(\alpha_i|x_{it}) = 0$

## 2. Long Answer II.

Let  $y_{it}$  denote the unemployment rate for city  $i$  at time  $t$ . You are interested in studying the effects of a state funded job training program on city unemployment rates. Let  $z_i$  denote a vector of *observed* time-constant city-specific variables that may influence the unemployment rate (these could include things like geographic location). Let  $x_{it}$  be a vector of time-varying factors that can affect the unemployment rate. The variable  $prog_{it}$  is the dummy indicator for program participation:  $prog_{it} = 1$  if city  $i$  participated at time  $t$ . Any sequence of program participation is possible, so that a city may participate in one year but not the next.

(a) [10] Consider the following pooled panel model

$$y_{it} = \beta_0 + z_i\gamma + x_{it}\beta_1 + \rho y_{it-1} + \delta prog_{it} + \varepsilon_{it}.$$

Discuss the merits of including  $y_{i,t-1}$  and state an assumption that allows you to consistently estimate the parameters by pooled OLS.

- (b) [5] Evaluate the following statement: “The model above is of limited value because the pooled OLS estimators are inconsistent if the  $\{\varepsilon_{it}\}$  are serially correlated.”
- (c) [5] Suppose that it is more realistic to assume that program participation depends on time-constant, unobserved city heterogeneity, but not directly on past unemployment. Write down a model that allows you to estimate the effectiveness of the program in this case. Explain how to estimate the parameters, describing any minimal assumptions you need.

- (d) [5] Suppose  $prog_{it}$  can depend on unobserved city heterogeneity as well as the past unemployment history. Explain how to consistently estimate the effect of the program, again stating minimal assumptions.

### 3. Long Answer III.

Consider the following panel data model:

$$y_{it} = \alpha_i + \beta^\top x_{it} + \varepsilon_{it},$$

where  $\alpha_i$  is a scalar with  $E(\alpha_i) = 0$  for all  $i = 1, \dots, n$ ,  $\beta = (\beta_1, \beta_2, \dots, \beta_k)^\top$  is a  $k \times 1$  vector of parameter,  $x_{it} = (x_{it,1}, \dots, x_{it,k})^\top$  is a  $k \times 1$  vector of exogenous variables, and  $\varepsilon_{it}$  is an error term,  $E(\varepsilon_{it}) = 0$ ,  $E(\varepsilon_{it}^2) = \sigma^2$ . We assume large  $n$  and large  $T$  setup.

- (a) [10] Derive the first-differenced model. Assuming  $E(\Delta y_{it} | \Delta x_{it}) = \beta^\top \Delta x_{it}$ , explain how this assumption can be used to construct moment conditions,  $E[g(\Delta y_{it}, \Delta x_{it}, \beta)] = 0$ , for estimating  $\beta$ . Also write down the corresponding sample moment conditions and drive the method of moment estimator.

- (b) [5] Now we assume  $E(\Delta x_{it} \Delta \varepsilon_{it}) \neq 0$ . Suppose we have a number of valid instruments  $z_{it}$  and the dimension of  $z_{it}$ ,  $m$ , is larger than the number of parameters  $k$ . Explain how this assumption can be used to construct a new moment condition,  $f(\beta) = E[f(\Delta y_{it}, \Delta x_{it}, z_{it}, \beta)] = 0$ . Write down the corresponding sample moment conditions  $f_{nT}(\beta)$ . Explain the intuition for the GMM estimator by referring to the quadratic form:

$$Q = f_{nT}(\beta)^\top W_m f_{nT}(\beta).$$

Explain the role of the weight matrix  $W_m$ , and how should it be optimally chosen?

**End of examination**

**Total pages: 9**

**Total marks: 100**